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this example we will
specify an element
edge length of 5 mm
(20 element divisions
along the line). Mesh
the frame Preprocessor
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*Optimal control theory
is a branch of
mathematical
optimization that deals
with finding a control*

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for a dynamical system
over a period of time
such that an objective
function is optimized.

*It has numerous
applications in science,
engineering and
operations research.*

*For example, the
dynamical system
might be a spacecraft
with controls
corresponding to
rocket thrusters, and
the objective might ...*

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Improper cleaning or sterilization of a patient-applied part may cause permanent damage. For cleaning and disinfection instructions, see the "Transducer Care" section. CAUTION Do not submerge the

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transducer connector
in solution. The cables
and transducer bodies
are liquid-tight, but the
connectors are not.

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Linear and Nonlinear Systems. A linear plant model is required for some of the control system design techniques covered in following chapters. In simple terms, a linear system produces an output that is

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*proportional to its
input. Small changes in
the input signal result
in small changes in the
output. Large changes
in the input cause
large changes in
output. A truly linear
system must respond
...*

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of the solution
procedure. Except
where a greater
accuracy is warranted,
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nonlinear history Use
case. The second
workflow is still very
easy: You're a lone
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want to use Mercurial*

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to keep track of your own changes and optimize your workflow. It works just like the log keeping workflow, with the difference that you go back to earlier changes at times and work onwards from there. To start a new project, you initialize a repository ...

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The longer time duration an input signal is applied to an integrator op amp, the _____ its output signal becomes. A. smaller B. Larger: Term. A. zero : Definition. UNIT 3 EXAM If the magnitude of the input signal applied to a

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*differentiator op amp is
large and unchanged,
its output signal is*

*_____ . A. zero B. small
C. large: Term. Gain =
(1/40) * 100 = 2.5:
Definition. Calculate
the gain of ...*

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allows you to control
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mouse, or remote control (there is no LIRC support - configure remotes as input devices instead). See the --input-options for ways to customize it. The following listings are not necessarily complete. See etc/input.conf for a list of default bindings. User input.conf ...

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The aim of this tutorial is to give an introductory overview of the finite element method (FEM) as it is implemented in NDSolve. The notebook introduces finite element method concepts for solving partial differential equations (PDEs).

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First, typical workflows are discussed. The setup of regions, boundary conditions and equations is followed by the solution of the PDE with NDSolve.

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